

On the origin of gravity and the law of
Newton, JHEP 04(2011)029

の "イントロ-力" の説明が 無茶苦茶
である。

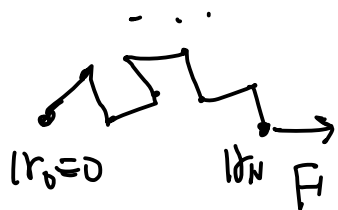
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\mathcal{P} : microscopic coordinate : $\mathcal{P} = (r_1, \dots, r_N, p_1, \dots, p_N)$
 $H_0(\mathcal{P})$: Hamiltonian for a polymer $r = (x, y, z)$

$$\Omega(E, x) \equiv \int d\mathcal{P} \delta(H_0(\mathcal{P}) - E) \cdot \delta(x_N - x)$$

\Rightarrow (2.1) ok \bar{F} : external force



$$\begin{aligned} Z(T, \bar{F}) &\equiv \int d\mathcal{P} e^{-\beta(H_0(\mathcal{P}) - \bar{F}x_N)} \\ &= \int d\mathcal{P} \int dE \delta(H_0(\mathcal{P}) - E) \int dx \delta(x_N - x) e^{-\beta(H_0(\mathcal{P}) - \bar{F}x)} \\ &= \int dE dx e^{-\beta(E - \bar{F}x)} \Omega(E, x) \end{aligned}$$

(2.2) の \bar{F} の前の符号は誤り

microcanonical ensemble (E, x) fixed

\bar{F}_{el} : 復元力

$$\Rightarrow dS = \frac{1}{T} dE + \frac{\bar{F}_{el}}{T} dx$$

\therefore

e.g. $\bar{F}_{el} = - \left\langle \frac{\partial H_0}{\partial x_N} \right\rangle_{E, x}^{mc}$

(2.3) は誤り

($\because \bar{F} + \bar{F}_{el} = 0$)

Microcanonical ensemble (with E_{tot}, \bar{F} : fixed)

に よる 変分原理の導出

$$\text{設定} \left\{ \begin{array}{l} H(P) = H_0(P) - \bar{F}x_N = E_{\text{tot}} : \text{fix} \\ \bar{F} : \text{fix} \end{array} \right.$$

$$\begin{aligned} \rho(x) &= \int dP \frac{\delta(H_0(P) - \bar{F}x_N - E_{\text{tot}}) \delta(x_N - x)}{\tilde{\Omega}(E_{\text{tot}}, \bar{F})} \\ &= \frac{1}{\tilde{\Omega}(E_{\text{tot}}, \bar{F})} \int dP \delta(H_0(P) - (E_{\text{tot}} + \bar{F}x)) \cdot \delta(x_N - x) \\ &= \frac{1}{\tilde{\Omega}(E_{\text{tot}}, \bar{F})} \Omega(E_{\text{tot}} + \bar{F}x, x) \\ &= \text{const} \circ \frac{1}{k_B} S(E_{\text{tot}} + \bar{F}x, x) \end{aligned}$$

よって x を決める変分原理は $\frac{d}{dx} S(E_{\text{tot}} + \bar{F}x, x) = 0$

(2-4)式は 符号ミスでたまたま"レベル"の
全しの意味不明.